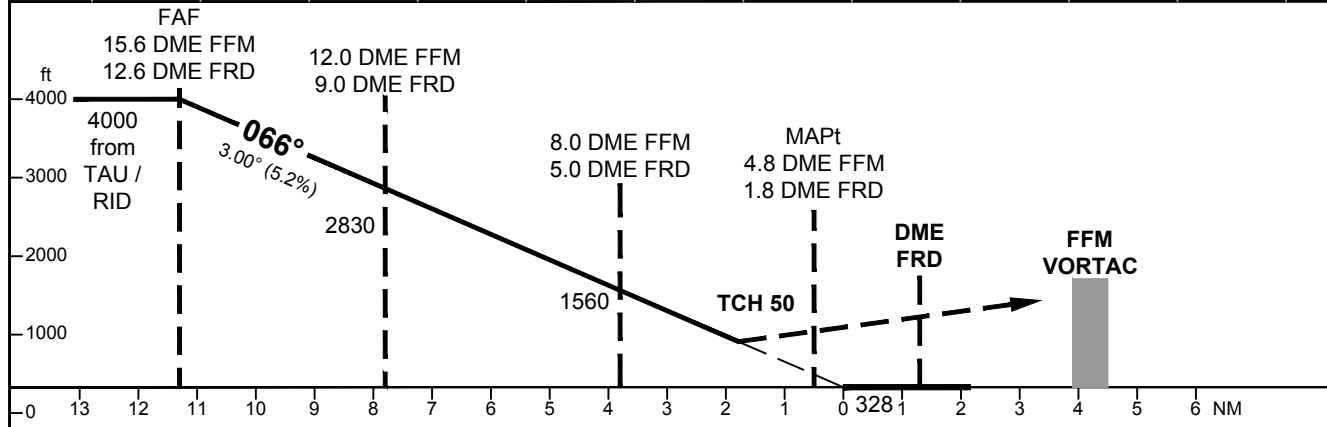
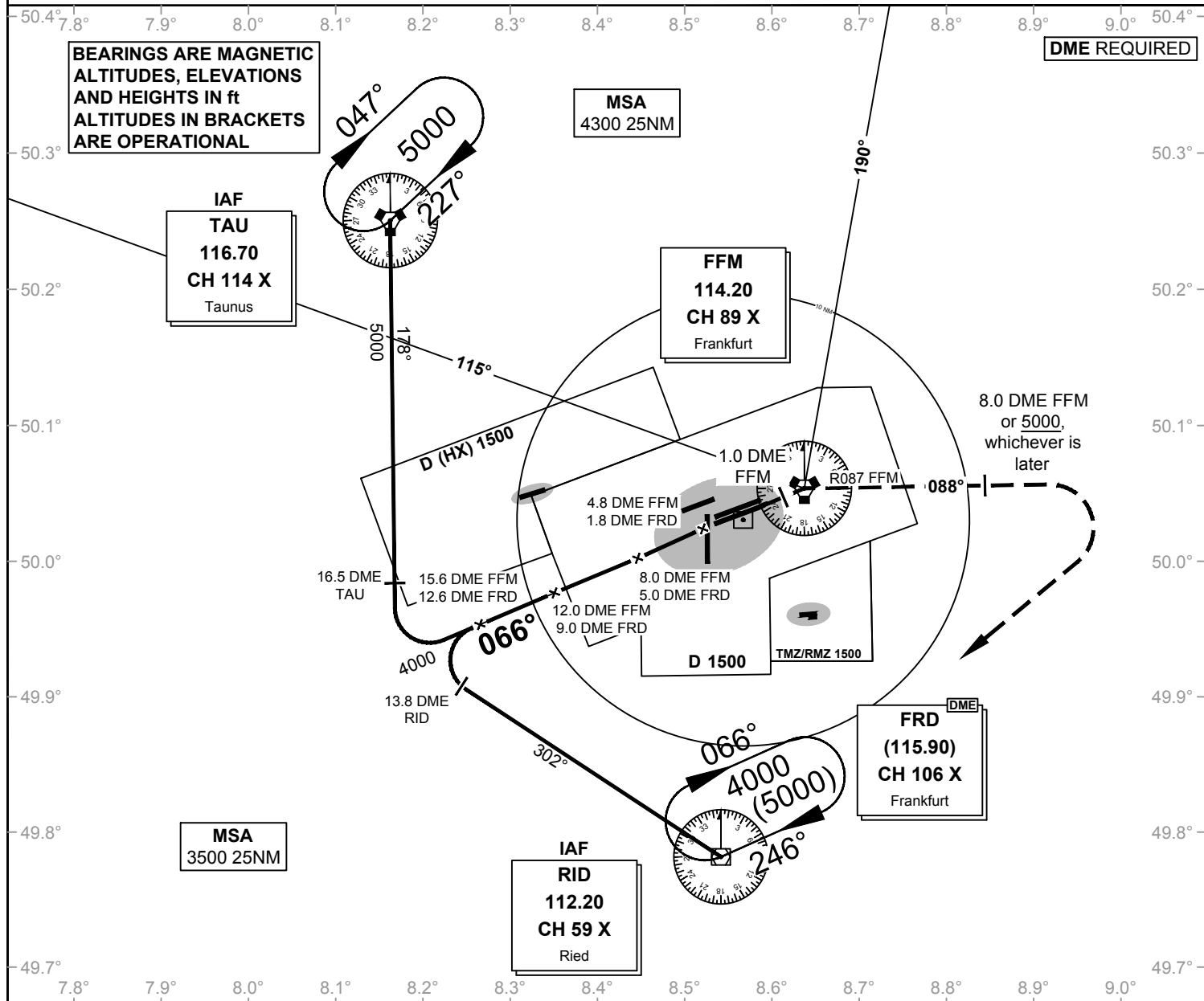


VATSIM Germany Instrument Approach Chart

**Frankfurt Main
EDDF
VOR
RWY 07R**

Elevation: THR07R ELEV 328
 Langen Radar (N) 120.800
 Langen Radar (S) 125.350
 Director (N) 127.270
 Director (S) 118.500
 Tower 119.900
 Tower (W) 124.850
 ATIS 118.020

VAR: 1° E



OCA (OCH)	VOR/DME
CAT A	800 (480)
CAT B	800 (480)
CAT C	810 (480)
CAT D	810 (480)

MISSED APPROACH: Climb straight ahead to 1.0 DME inbound FFM; RT, intercept R088 FFM outbound to 8.0 DME FFM or 5000, whichever is later; RT to RID DVOR/DME, maintain 5000.

DME FFM	15	14	13	12	11	10	9	8	7	6	GS	kt	80	100	120	140	160	180
DIST THR	10.7	9.7	8.7	7.7	6.7	5.7	4.7	3.7	2.7	1.7	8DME FFM / 5DME FRD - MAPt(3.2NM)	MIN:SEC	2:24	1:55	1:36	1:22	1:12	1:06
ALTITUDE	3790	3470	3150	2830	2520	2200	1880	1560	1240	920	Rate of descent (5.2%)	ft / MIN	420	530	640	740	850	960

Timing not authorized for defining the MAPt.

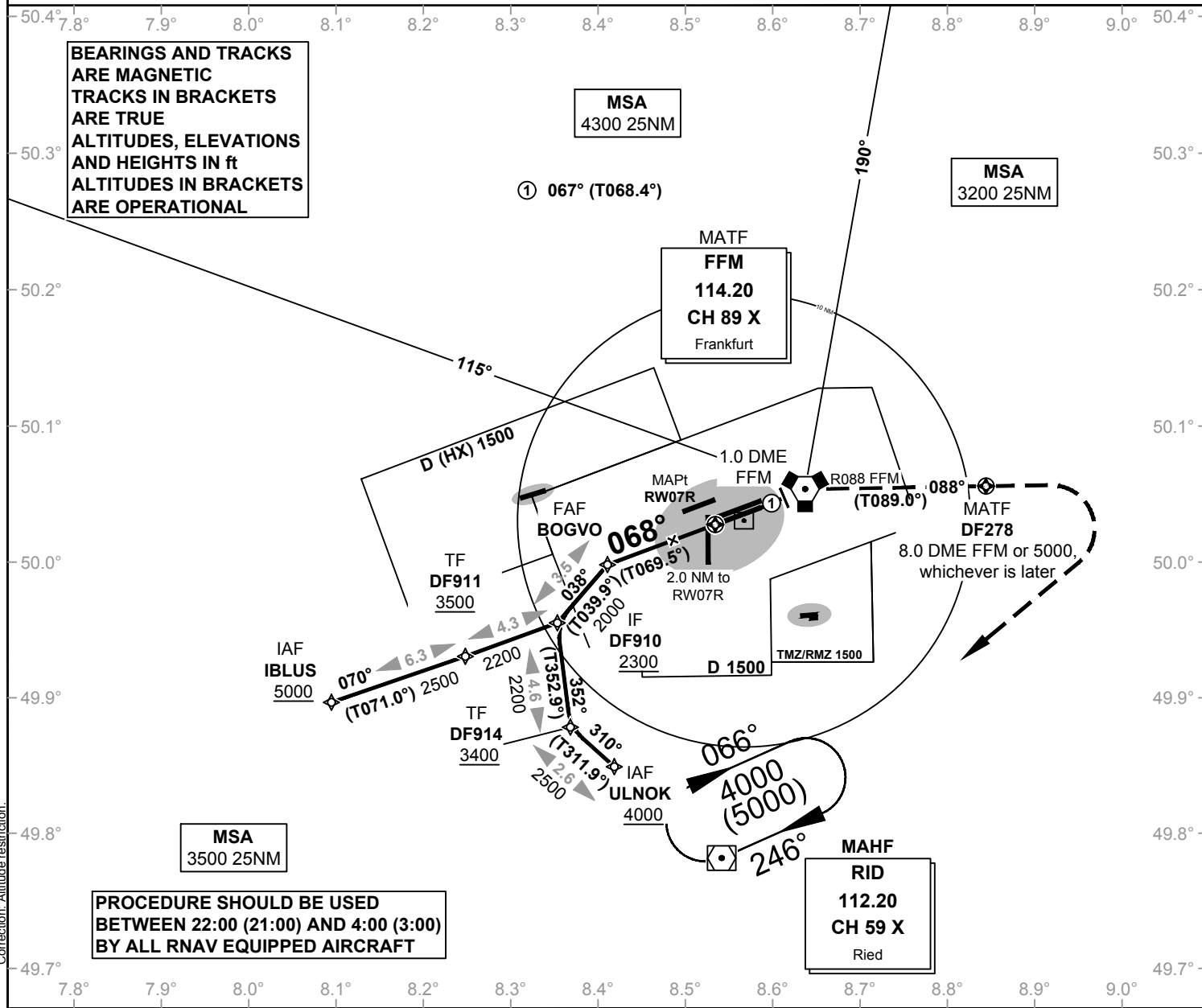
VATSIM Germany Instrument Approach Chart

**Frankfurt Main
EDDF
RNAV (GPS) Y
RWY 07R**

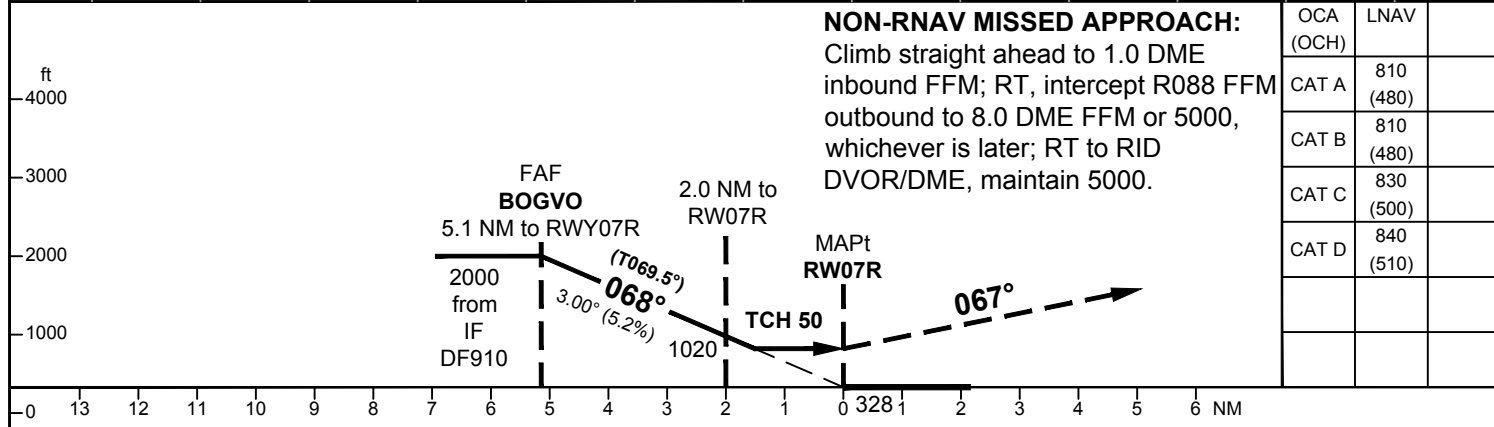
Elevation: THR07R ELEV 328
 Langen Radar (N) 120.800
 Langen Radar (S) 125.350
 Director (N) 127.270
 Director (S) 118.500
 Tower 119.900
 Tower (W) 124.850
 ATIS 118.020

VAR: 1° E

**BEARINGS AND TRACKS
ARE MAGNETIC
TRACKS IN BRACKETS
ARE TRUE
ALTITUDES, ELEVATIONS
AND HEIGHTS IN ft
ALTITUDES IN BRACKETS
ARE OPERATIONAL**



Correction: Altitude restriction.



NON-RNAV MISSED APPROACH:
 Climb straight ahead to 1.0 DME
 inbound FFM; RT, intercept R088 FFM
 outbound to 8.0 DME FFM or 5000,
 whichever is later; RT to RID
 DVOR/DME, maintain 5000.

OCA (OCH)	LNAV
CAT A	810 (480)
CAT B	810 (480)
CAT C	830 (500)
CAT D	840 (510)

MISSED APPROACH: Climb on track 067° to FFM; RT on track 088° to DF278 or 5000, whichever is later; RT to RID, maintain 5000.
RNAV (GPS) FFM[R] - DF278[A5000; R] - RID[A5000]

DIST THR	4	3	2						
ALTITUDE	1660	1340	1020						

GS	kt	80	100	120	140	160	180
TIXAK - RW07C (5.1 NM)	MIN:SEC	3:50	3:04	2:33	2:11	1:55	1:42
Rate of descent (5.2%)	ft / MIN	420	530	640	740	850	960

Timing not authorized for defining the MAPt.

